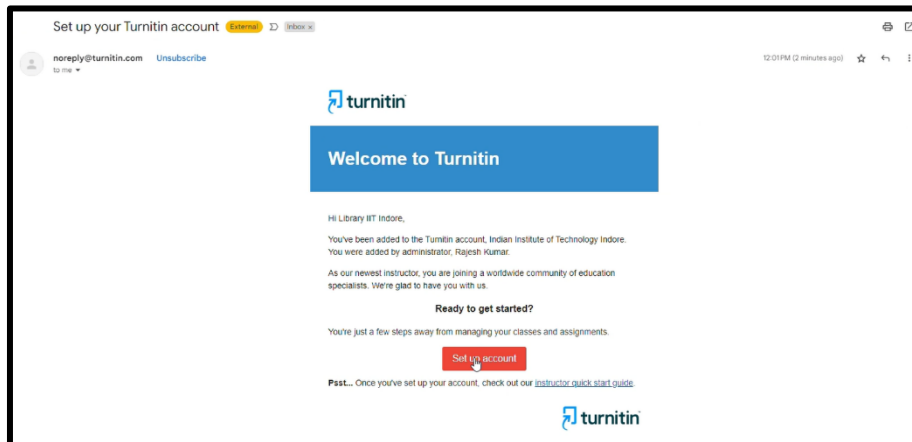# MANUAL TO SETUP THE TURNITIN INSTRUCTOR ACCOUNT
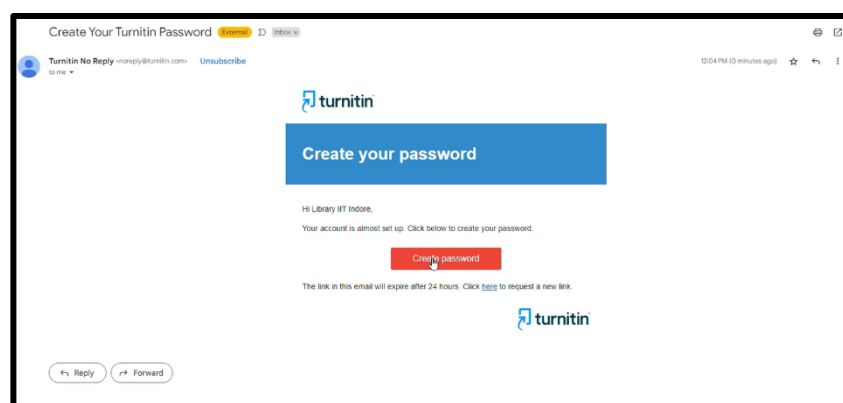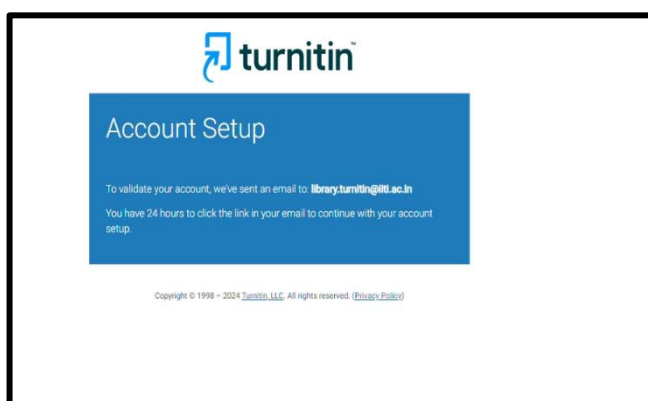

1. Click on the link received in the email from Turnitin Instructor Account setup

2. Enter your registered institutional email ID and name

3. You will receive an email to set your password on registered email id.

4. Click on the link and set your password.

5. Login using the email id and password
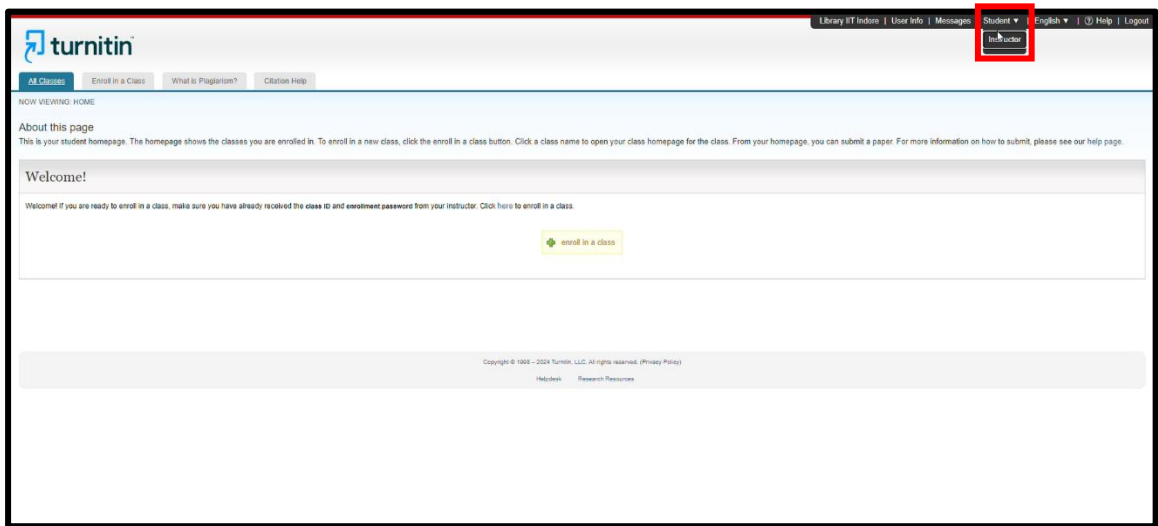
6. Change the interface from Student to Instructor
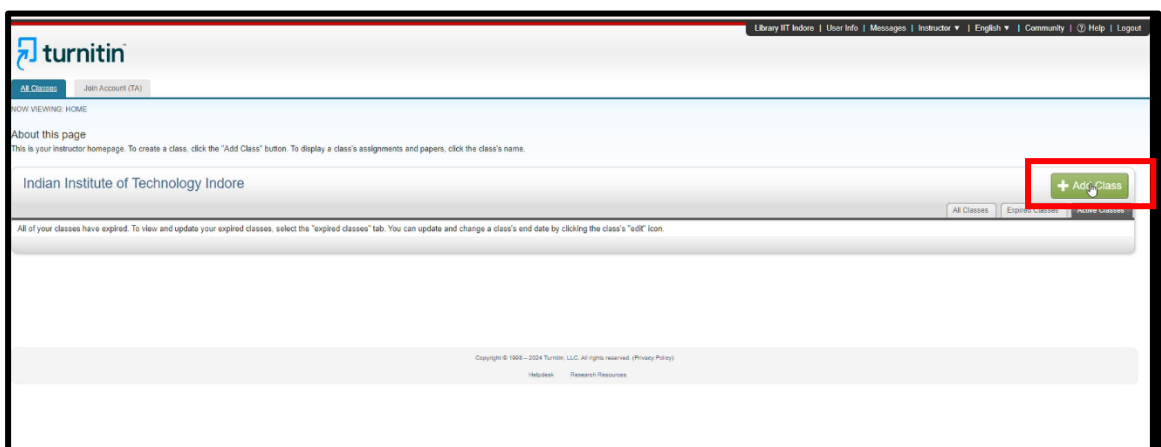
7. Click on "Add Class"

8. Enter the required details and provide the Enrolment Key.

9. Write down the Class ID and Enrolment Key for future reference.
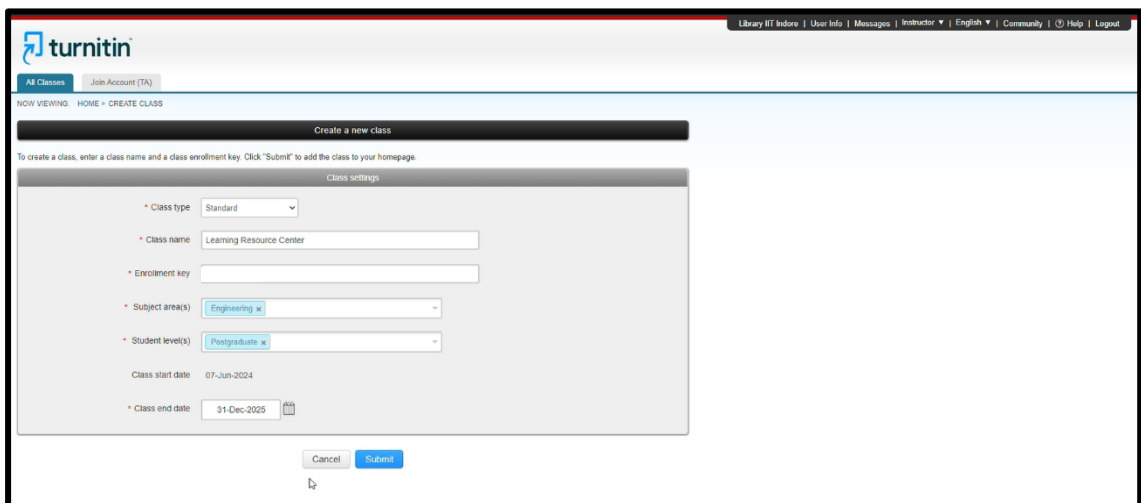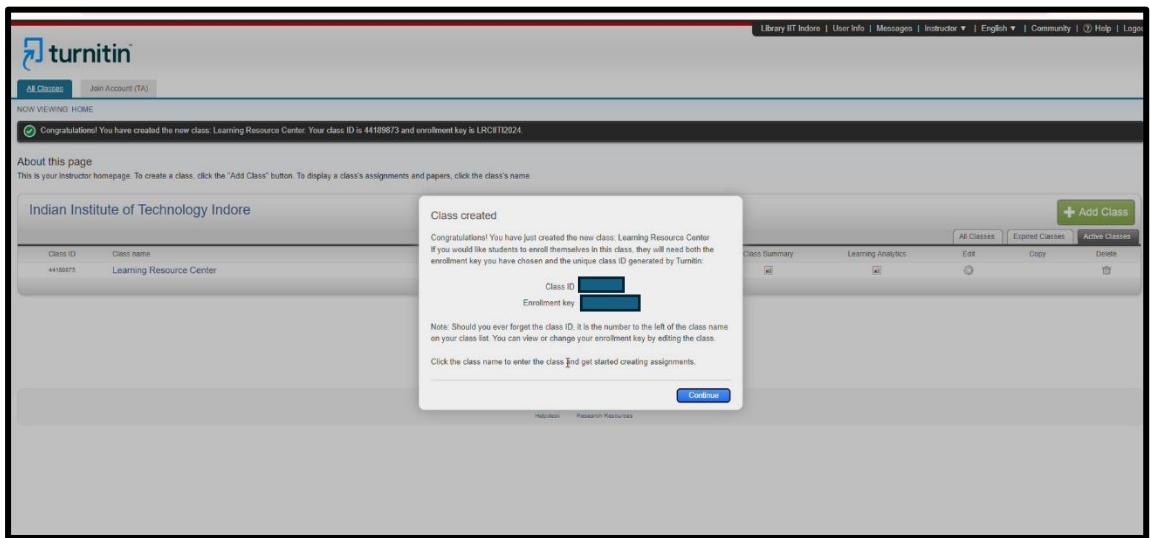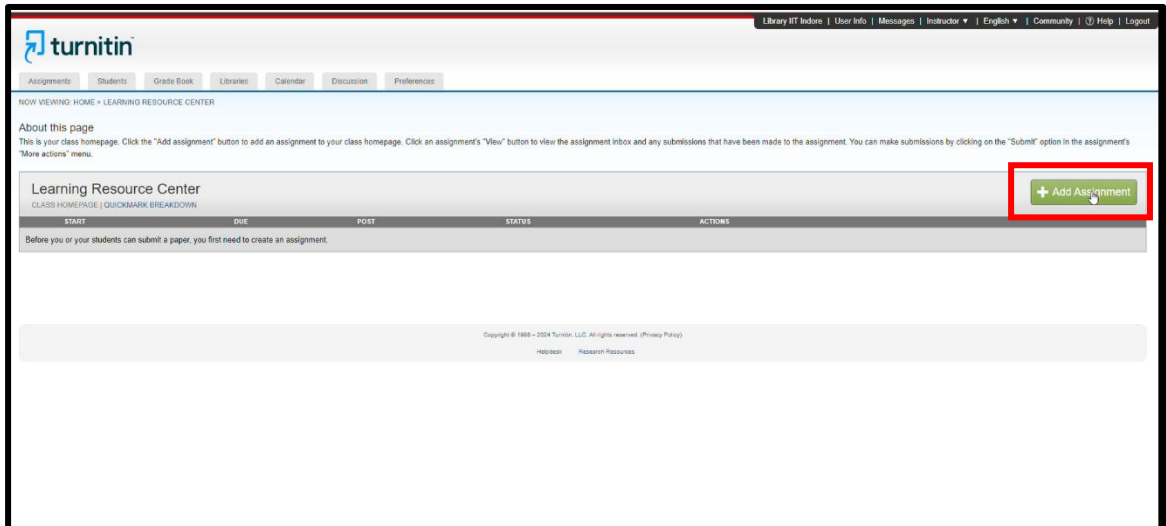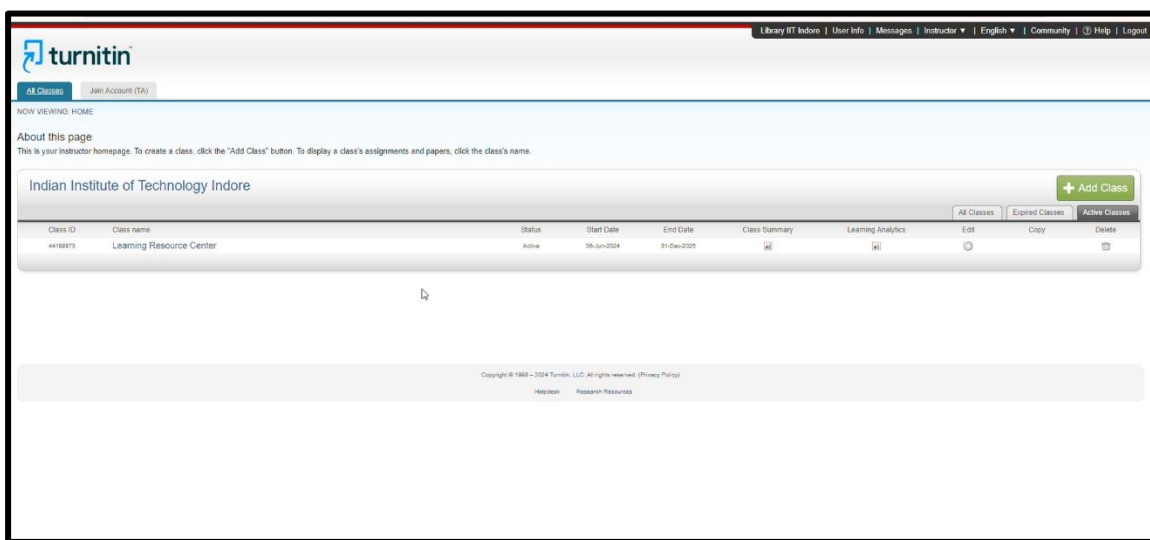

10. Open the class and "Add Assignment"

11. Fill up the details in the assignment as displayed and click Create Assignment.

12. Once the assignment is created, click on the View.
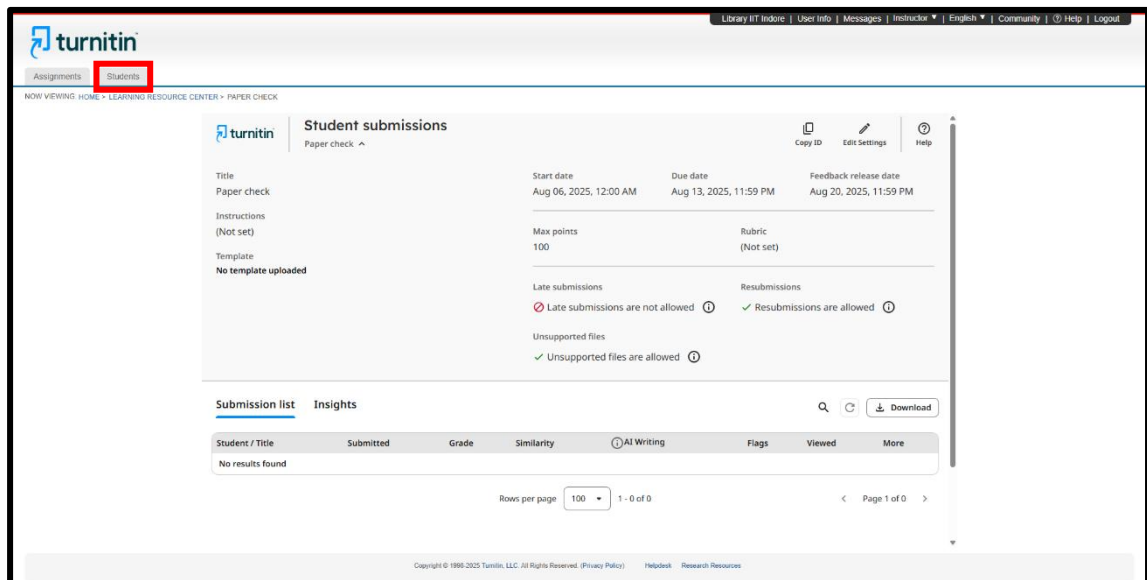
13. Open the assignment and go to "Student" Tab.
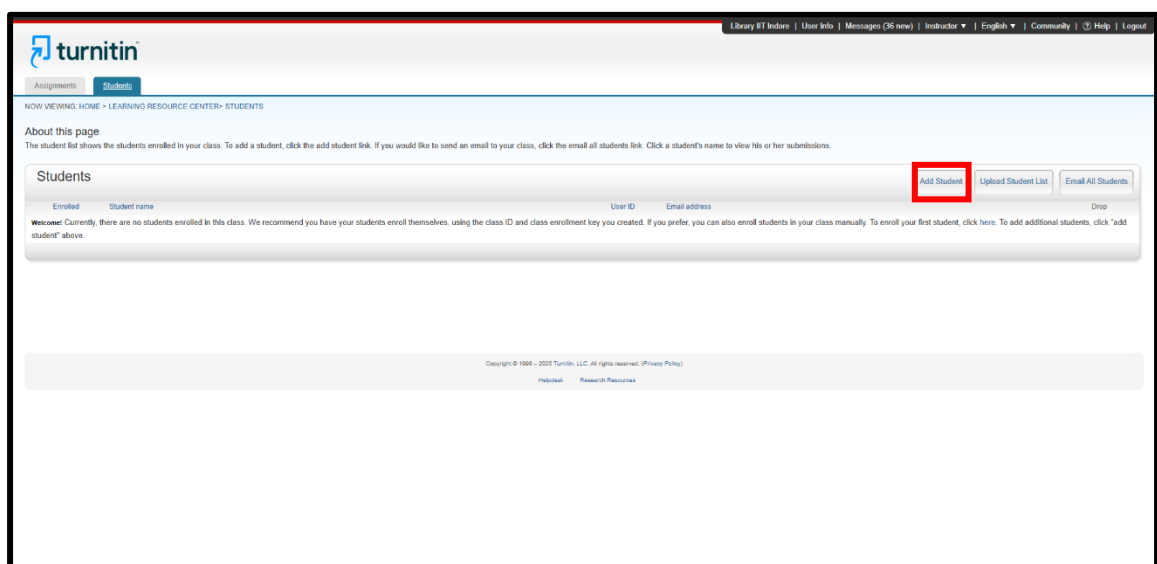
14. Click on "Add Student".
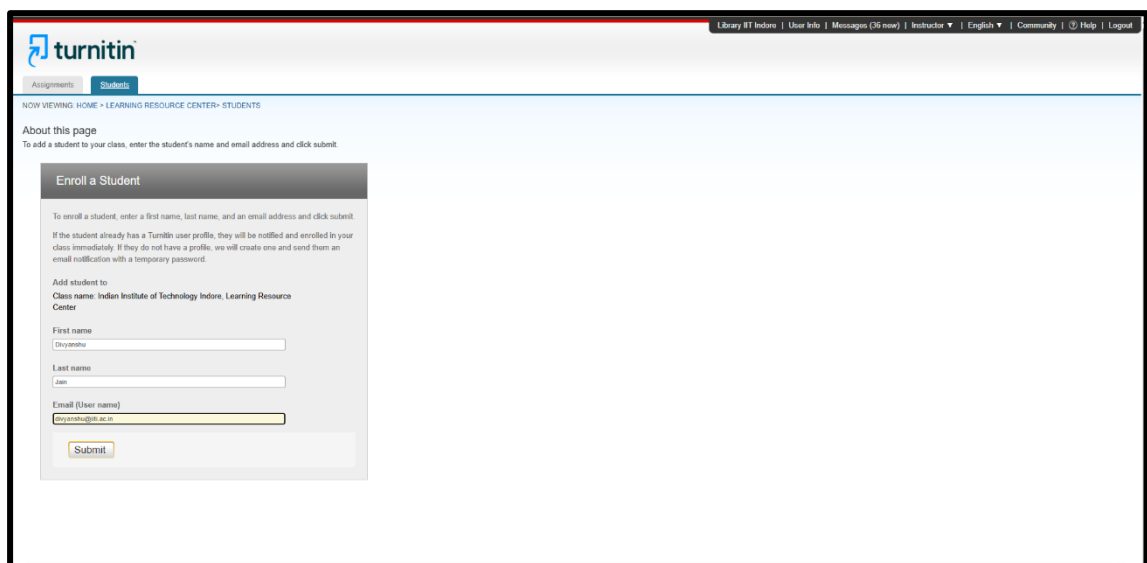
15. Enter the details of Student and Submit.
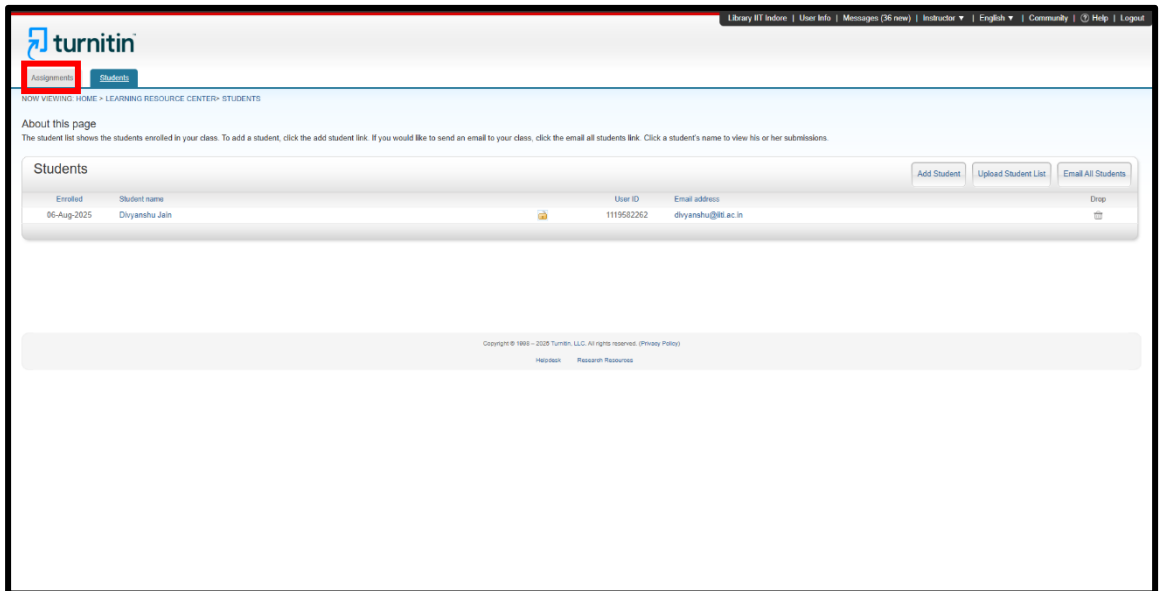
16. Go to Assignment Tab.
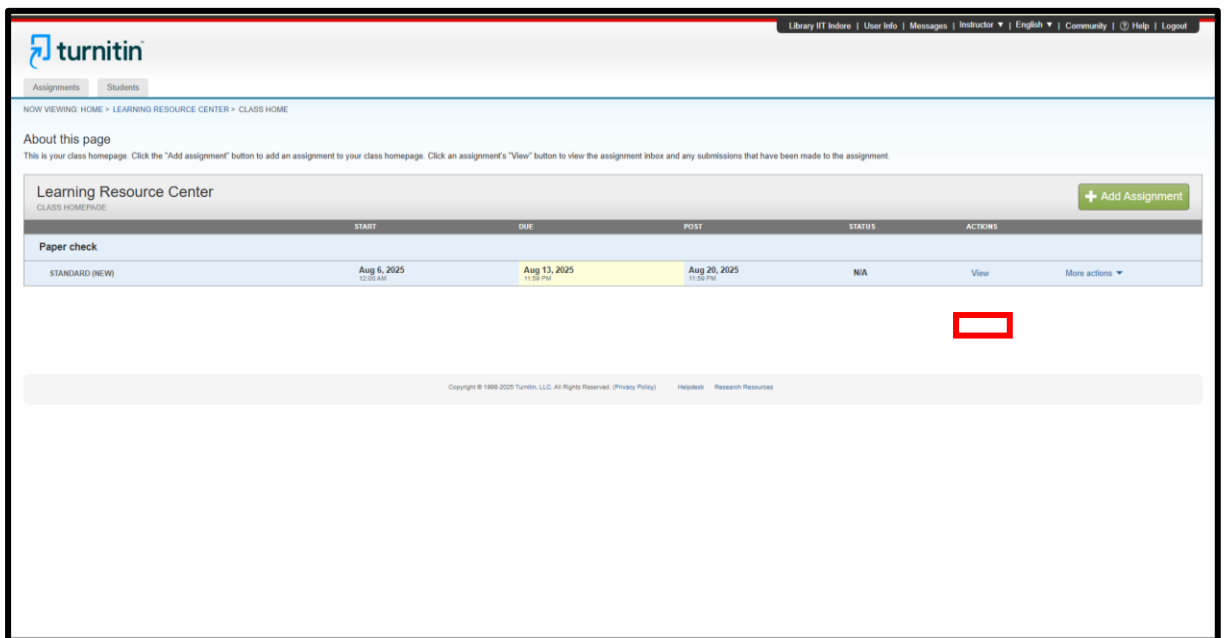
17. Open the assignment by clicking on view.
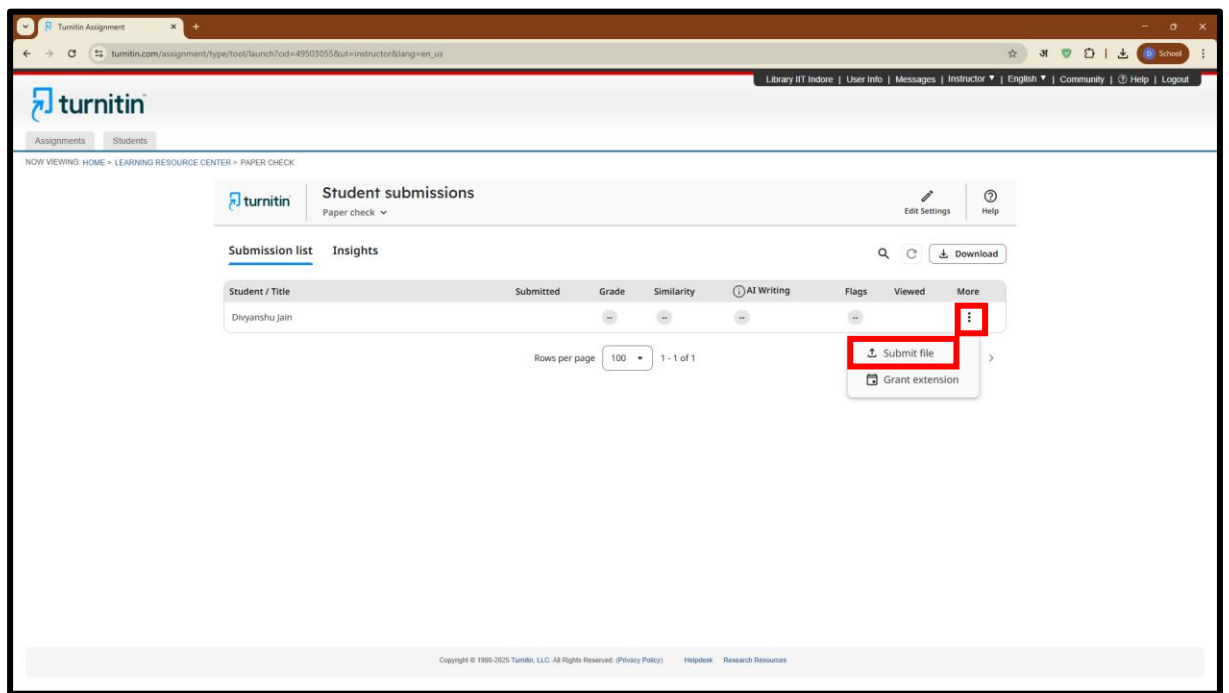
18. Click on three vertical dots and then Submit file against the name of respective users.

If there are so many students, the instructor can search their name by clicking on 🔍.
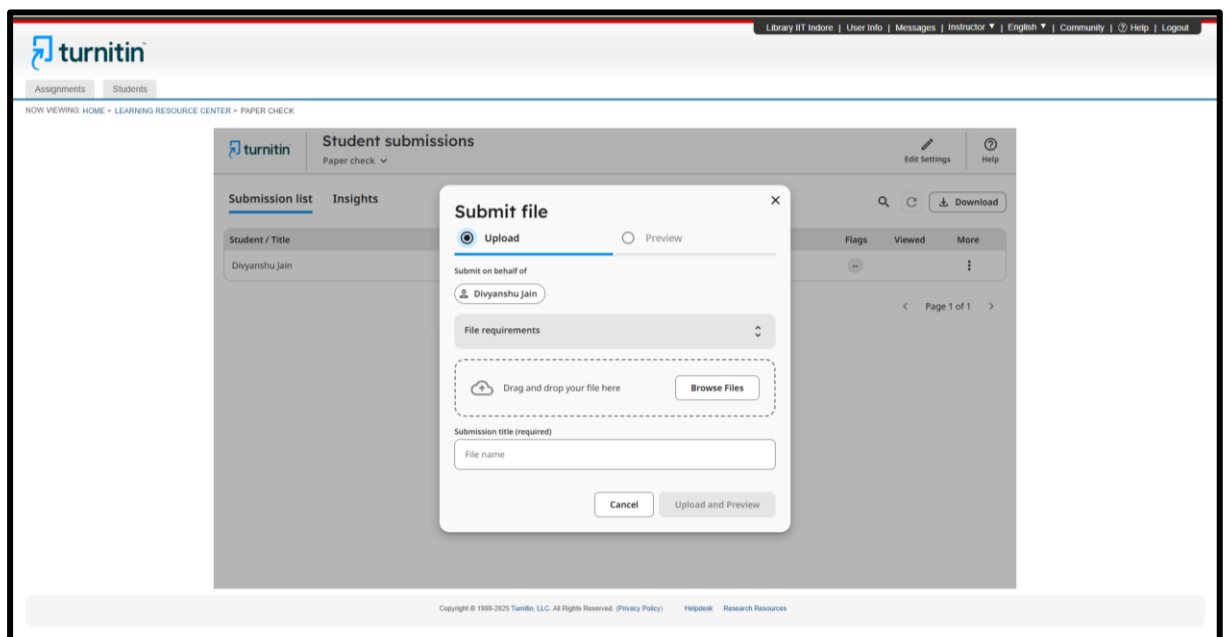
19. Once you click Submit File, you must Browse or Drag and drop the file to be check for similarity report and click on Upload and Preview.
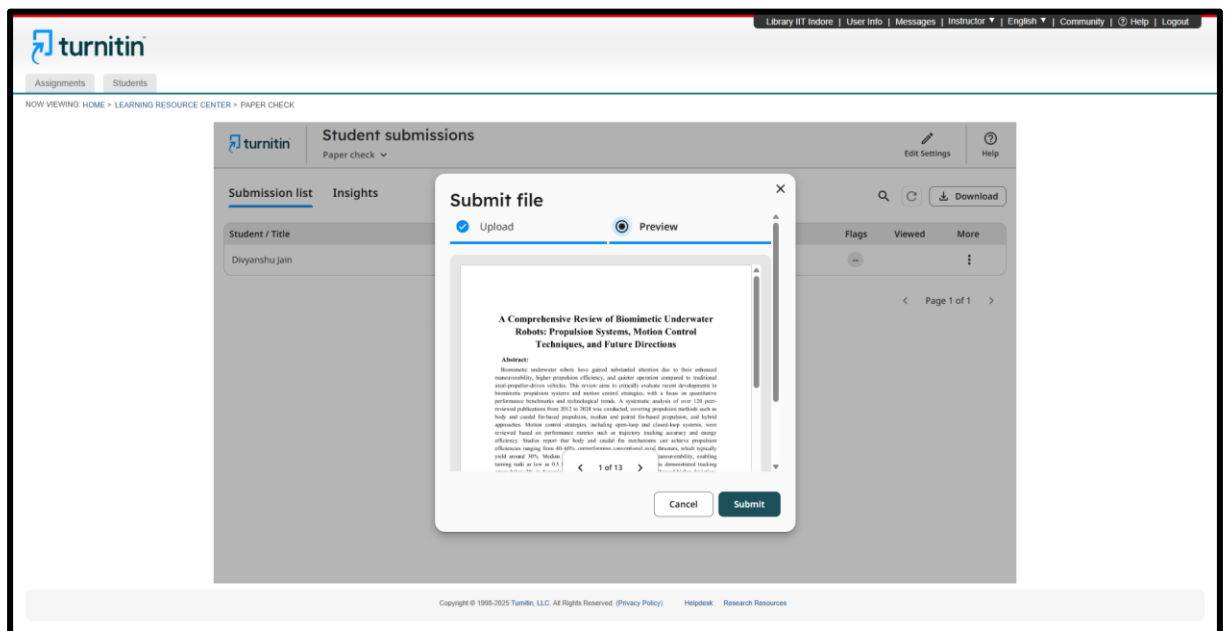
20. After preview generated, click on Submit.
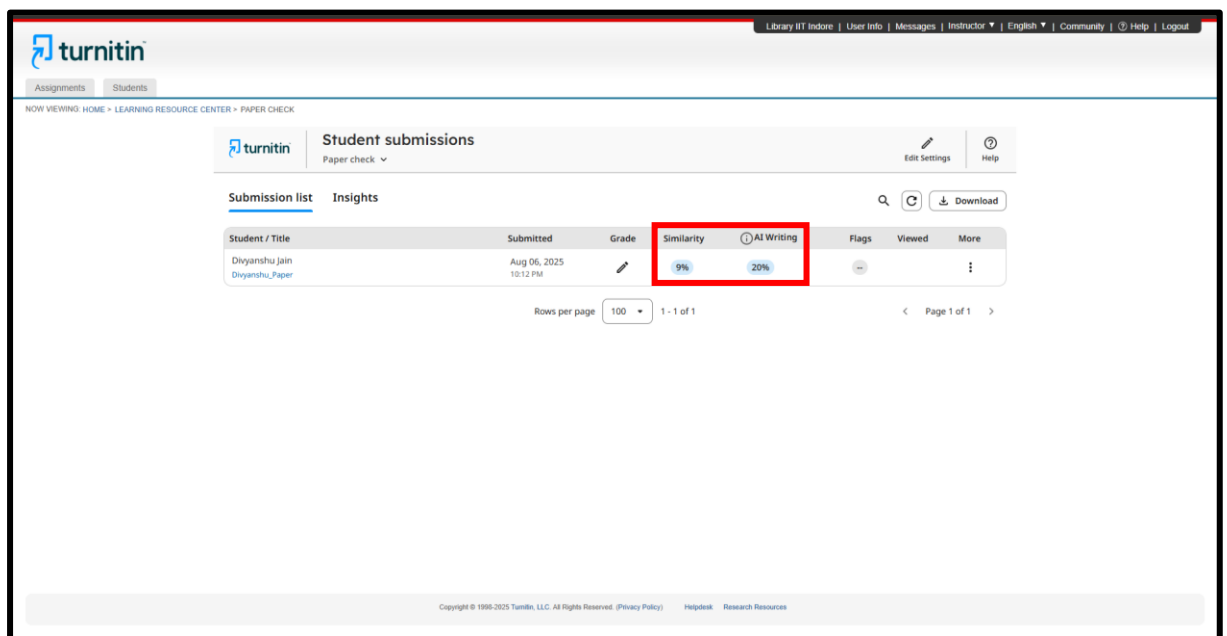
21. After some time of submission, Similarity report and AI Writing report will be generated. You can see the report by clicking on the percentage.

Abstract:

Biomimetic underwater robots have gained substantial attention due to their enhanced maneuverability, higher propulsion efficiency, and quieter operation compared to traditional axial-propeller-driven vehicles. This review aims to critically evaluate recent developments in biomimetic propulsion systems and motion control strategies, with a focus on quantitative performance benchmarks and technological trends. A systematic analysis of over 120 peer-reviewed publications from 2012 to 2024 was conducted, covering propulsion methods such as body and caudal fin-based propulsion, median and paired fin-based propulsion, and hybrid control strategies, including open-loop and closed-loop systems, were performance metrics such as trajectory tracking accuracy and energy

22. Once the report is open, it can be downloaded by clicking on the download button available on the top right corner of the screen.